

IN THE SPECIFICATION:

Kindly delete the paragraph beginning on page 13, line 19, and replace with the following paragraph:

The articulated arm 210A includes a plurality of links 220 connected together at joints 222. Articulated arm 210A has appropriately positioned electric motors to provide for feedback as described in greater detail below. Furthermore, appropriately positioned positional sensors, e.g., encoders, or potentiometers, or the like, are positioned on the joints 222 so as to enable joint positions of the master control to be determined as further described herein below. Axes A, B, and C indicate the positional degrees of freedom of articulated arm 210A. In general, movement about joints of the master control 210B primarily accommodates and senses orientational movement of the end effector, and movement about the joints of arm 210A primarily accommodates and senses translational movement of the end effector. The master control 210 is described in greater detail in U.S. Provisional Patent Application Serial No. 60/111,710, and in U.S. Patent Application No. 09/398,507, now U.S. Patent No. 6,714,839 (Attorney Docket No. 17516-001410), the full disclosures of which are incorporated herein by reference.